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L42 same (encircl$3 or circular$3 or circle$1 or spher$5 or ring$2)	12

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L1	(calibrat$3 or align$5 or adjust$6) with camera with (pattern or figure)	951	L1
L2	L1 same (image near6 process$3)	109	L2
L3	L2 same shape$1	4	L3
L4	camera near2 calibrat$5	1188	L4
L5	L4 same (pattern or figure)	194	L5
L6	L5 same image	107	L6
L7	L6 same shape$1	0	L7
L8	L6 same process$3	48	L8
L9	L8 same pattern	46	L9
L10	circular near5 bar near3 code	141	L10
L11	l4 and L10	0	L11
L12	l4 and (hough near3 transform$6)	23	L12
L13	L12 and (spher$5 or circle or circular$3 or ring)	11	L13

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DB=USPT,EPAB,JPAB,DWPI; PLUR=YES; OP=ADJ

L14	camera near3 calibrat$4	2111	L14
L15	L14 same ((geometric$5 or circle or circular$3 or ring or spher$5) near10 pattern)	18	L15

DB=DWPI; PLUR=YES; OP=ADJ

L16	wo96/359973-$.did.	0	L16

DB=USPT; PLUR=YES; OP=ADJ

L17	wo96/359973-$.did.	0	L17
L18	camera image calibration	4	L18
L19	camera near3 calibrat$4 near10 pattern	97	L19
L20	L19 same (circular or circle or ring or spher$4)	4	L20
L21	(fingerprint$3 or biometric) same (gun or revolver or bullet)	103	L21
L22	L21 same finger	13	L22
L23	fbi and mariam	2	L23
L24	(calibrat$3 near2 camera) same digit$5 same imag$3 same process$3	43	L24
L25	L24 same (shape$1 or pattern)	8	L25
L26	circular near3 bar code	57	L26
L27	l26 and (camera near5 calibrat$4)	0	L27
L28	(barcode or bar-code or bar code) and (camera near5 calibrat$4)	104	L28
L29	L28 and ((spher$5 or circular or circle) near10 pattern)	25	L29
L30	(image near10 pattern near10 (camera near5 calibrat$4))	32	L30
L31	L30 same (circle or ring or spher$5 or circular)	0	L31
L32	L30 and (circle or ring or spher$5 or circular)	8	L32
L33	l4 same edge	51	L33
L34	L33 same (translat$4 or transform$6)	5	L34
L35	L34 same distance	1	L35
L36	(edge near5 point) same camera same calibrat$5 same image	24	L36
L37	L36 same distance	4	L37
L38	L36 same (center or centre or central)	7	L38
L39	L38 same distance	2	L39
L40	(calibrat$3 near3 (pattern or figure))	1600	L40
L41	L40 same camera	143	L41
L42	L41 same image	101	L42
L43	L42 same (encircl$3 or circular$3 or circle$1 or spher$5 or ring$2)	12	L43

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1 **Pipe inspection using a laser-based transducer and automated anal· techniques**
Duran, O.; Althoefer, K.; Seneviratne, L.D.;
Mechatronics, IEEE/ASME Transactions on , Volume: 8 , Issue: 3 , Sept. 200:
Pages:401 - 409

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2 **Stereo vision in LHD automation**
Whitehorn, M.; Vincent, T.; Debrunner, C.H.; Steele, J.;
Industry Applications, IEEE Transactions on , Volume: 39 , Issue: 1 , Jan.-Fel 2003
Pages:21 - 29

[Abstract]   [PDF Full-Text (1010 KB)]   **IEEE JNL**

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3 **Sensor integration in airborne mapping**
Toth, C.K.;
Instrumentation and Measurement, IEEE Transactions on , Volume: 51 , Issu 6 , Dec. 2002
Pages:1367 - 1373

[Abstract]   [PDF Full-Text (2300 KB)]   **IEEE JNL**

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4 **MISR in-flight camera geometric model calibration and georectificat performance**
Jovanovic, V.M.; Bull, M.A.; Smyth, M.M.; Jia Zong;
Geoscience and Remote Sensing, IEEE Transactions on , Volume: 40 , Issue: 7 , July 2002
Pages:1512 - 1519

[Abstract]   [PDF Full-Text (379 KB)]   **IEEE JNL**

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5 **Early validation of the Multi-angle Imaging SpectroRadiometer (MI!**
radiometric scale
Bruegge, C.J.; Chrien, N.L.; Ando, R.R.; Diner, D.J.; Abdou, W.A.; Helmlinge
M.C.; Pilorz, S.H.; Thome, K.J.;
Geoscience and Remote Sensing, IEEE Transactions on , Volume: 40 , Issue:
7 , July 2002
Pages:1477 - 1492

[Abstract]   [PDF Full-Text (571 KB)]   **IEEE JNL**

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6 **Multi-angle Imaging SpectroRadiometer (MISR) on-board calibratoı**
(OBC) in-flight performance studies
Chrien, N.L.; Bruegge, C.J.; Ando, R.R.;
Geoscience and Remote Sensing, IEEE Transactions on , Volume: 40 , Issue:
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Pages:1493 - 1499

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multiple cameras
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Systems, Man and Cybernetics, Part A, IEEE Transactions on , Volume: 31 , I
1 , Jan. 2001
Pages:43 - 54

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8 **Differential absorption techniques and radiometric satellite calibrat**
for measuring air-sea interactions
McKeown, W.;
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5 , Sept. 2000
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9 **MISR prelaunch instrument calibration and characterization results**
Bruegge, C.J.; Duval, V.G.; Chrien, N.L.; Korechoff, R.P.; Gaitley, B.J.; Hochl
E.B.;
Geoscience and Remote Sensing, IEEE Transactions on , Volume: 36 , Issue:
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Pages:1186 - 1198

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multispectral digital camera system
Stow, D.; Hope, A.; Nguyen, A.T.; Phinn, S.; Benkelman, C.A.;
Geoscience and Remote Sensing, IEEE Transactions on , Volume: 34 , Issue:

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5 , Sept. 1996
Pages:1191 - 1203

[Abstract]   [PDF Full-Text (1780 KB)]   **IEEE JNL**

**11 Demonstration of a high-fidelity predictive/preview display techni
for telerobotic servicing in space**
Kim, W.S.; Bejczy, A.K.;
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12 Calibration of the CCRS airborne scatterometers
Hawkins, R.K.; Farris-Manning, P.J.; Gibson, J.R.; Singh, K.;
Antennas and Propagation, IEEE Transactions on , Volume: 38 , Issue: 6 , Jui
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Pages:903 - 918

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13 A conical panoramic stereo imaging system for 3-D scene reconstruction
Firoozfam, P.; Negahdaripour, S.; Barufaldi, C.;
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Pages:2303 - 2308 Vol.4

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14 Multi-camera conical imaging; calibration and robust 3-D motion estimation for ROV based mapping and positioning
Firoozfam, P.; Shahriar Negahdaripour;
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15 SPOT5 geometric image quality
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Pages:303 - 305 vol.1

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1 **Autocalibration & 3D reconstruction with non-central catadioptric cameras**
Micusik, B.; Pajdla, T.;
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Pages:58 - 65

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2 **Autocalibration of a projector-screen-camera system: theory and algorithm for screen-to-camera homography estimation**
Okatani, K.; Deguchi, K.;
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16 Oct. 2003
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3 **Globally convergent autocalibration**
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1 **An efficient solution to the five-point relative pose problem**
Nister, D.;
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Pages:756 - 770

[Abstract]   [PDF Full-Text (1512 KB)]   **IEEE JNL**

2 **Uncalibrated Euclidean 3-D reconstruction using an active vision sy**
Li, Y.F.; Lu, R.S.;
Robotics and Automation, IEEE Transactions on , Volume: 20 , Issue: 1 , Feb.

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3 **Multiple motion scene reconstruction with uncalibrated cameras**
Mei Han; Kanade, T.;
Pattern Analysis and Machine Intelligence, IEEE Transactions on , Volume: 25 , Issue: 7 , July 2003
Pages:884 - 894

[Abstract]   [PDF Full-Text (929 KB)]   **IEEE JNL**

4 **Vanishing point detection without any a priori information**
Almansa, A.; Desolneux, A.; Vamech, S.;
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5 Paracatadioptric camera calibration
Geyer, C.; Daniilidis, K.;
Pattern Analysis and Machine Intelligence, IEEE Transactions on , Volume:
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Pages:687 - 695

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6 A case against Kruppa's equations for camera self-calibration
Sturm, P.;
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22 , Issue: 10 , Oct. 2000
Pages:1199 - 1204

[Abstract]   [PDF Full-Text (172 KB)]   **IEEE JNL**

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7 Geometric camera calibration using circular control points
Heikkila, J.;
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22 , Issue: 10 , Oct. 2000
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8 A flexible new technique for camera calibration
Zhang, Z.;
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22 , Issue: 11 , Nov. 2000
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9 Stereo calibration from rigid motions
Horaud, R.; Csurka, G.; Demirdijian, D.;
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22 , Issue: 12 , Dec. 2000
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10 Monitoring activities from multiple video streams: establishing a common coordinate frame
Lee, L.; Romano, R.; Stein, G.;
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11 Stratified self-calibration with the modulus constraint
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from aerial imagery**
Shufelt, J.A.;
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21 , Issue: 4 , April 1999
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Basu, A.; Ravi, K.;
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Ling Ling Wang; Wen-Hsiang Tsai;
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16 **3-D position sensing using a passive monocular vision system**
Cardillo, J.; Sid-Ahmed, M.A.;
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17 **Camera calibration: a quick and easy way to determine the scale fa**
Penna, M.A.;
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Grosky, W.I.; Tamburino, L.A.;
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Cernuschi-Frias, B.; Cooper, D.B.; Hung, Y.-P.; Belhumeur, P.N.;
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20 **An overview of geometric modeling using active sensing**
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21 **Partial discharges in flat, dielectric/metallic bounded cavities**
Holboll, J.T.; Braun, J.M.; Fujimoto, N.; Stone, G.C.;
Science, Measurement and Technology, IEE Proceedings- , Volume: 142 , Issi
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22 **Camera center estimation**
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23 **Estimating sensor orientation in cameras**
Aggarwal, M.; Ahuja, N.;
Pattern Recognition, 2000. Proceedings. 15th International Conference
on , Volume: 1 , 3-7 Sept. 2000
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24 **Camera calibration and relative pose estimation from gravity**
Sturm, P.F.; Long Quan;
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on , Volume: 1 , 3-7 Sept. 2000
Pages:72 - 75 vol.1

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25 **Violating rotating camera geometry: the effect of radial distortion ‹
self-calibration**
Tordoff, B.; Murray, D.W.;
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on , Volume: 1 , 3-7 Sept. 2000
Pages:423 - 427 vol.1

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26 **Resolving ambiguities of self-calibration in turntable motion**

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Yong Liu; HuangTat Tsui; ChengKe Wu;
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27 **A neural optimization framework for zoom lens camera calibration**
Ahmed, M.T.; Farag, A.A.;
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28 **Stereo without depth search and metric calibration**
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29 **Catadioptric self-calibration**
Sing Bing Kang;
Computer Vision and Pattern Recognition, 2000. Proceedings. IEEE Conferenc
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30 **Recovering projection geometry: how a cheap camera can outperfc
an expensive stereo system**
Mischke, M.M.; Navab, N.;
Computer Vision and Pattern Recognition, 2000. Proceedings. IEEE Conferenc
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